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FORM PTO-1390 (REV. 5-93)		U.S. DEPARTMENT OF COMMERCE PATENT AND TRADEMARK OFFICE	CASE NO. 10541-1323
TRANSMITTAL LETTER TO THE UNITED STATES DESIGNATED/ELECTED OFFICE (DO/EO/US) CONCERNING A FILING UNDER 35 U.S.C. 371			U.S. APPLICATION NO. (If known, see 37 C.F.R. 1.5) <b>10/070884</b>
INTERNATIONAL APPLICATION NO. PCT/US00/26522	INTERNATIONAL FILING DATE 27 September 2000	PRIORITY DATE CLAIMED 27 September 1999	
TITLE OF INVENTION VEHICLE IMPACT SYSTEM			
APPLICANT(S) FOR DO/EO/US Paul K. Zoratti and David Ming Chi			
Applicant herewith submits to the United States Designated/Elected Office (DO/EO/US) the following items and other information:			
<p>1. <input checked="" type="checkbox"/> This is a FIRST submission of items concerning a filing under 35 U.S.C. 371</p> <p>2. <input type="checkbox"/> This is a SECOND or SUBSEQUENT submission of items concerning a filing under 35 U.S.C. 371</p> <p>3. <input checked="" type="checkbox"/> This express request to begin national examination procedures (35 U.S.C. 371(f)) at any time rather than delay examination until the expiration of the applicable time limit set in 35 U.S.C. 371(b) and PCT Articles 22 and 39(1).</p> <p>4. <input checked="" type="checkbox"/> A proper Demand for International Preliminary Examination was made by the 19th month from the earliest claimed priority date.</p> <p>5. <input checked="" type="checkbox"/> A copy of the International Application as filed (35 U.S.C. 371(c)(2)).</p> <p>    a. <input type="checkbox"/> is transmitted herewith (required only if not transmitted by the International Bureau).</p> <p>    b. <input type="checkbox"/> has been transmitted by the International Bureau.</p> <p>    c. <input checked="" type="checkbox"/> is not required, as the application was filed in the United States Receiving Office (RO/US).</p> <p>6. <input type="checkbox"/> A translation of the International Application into English (35 U.S.C. 371(c)(2)).</p> <p>7. <input checked="" type="checkbox"/> Amendments to the claims of the International Application under PCT Article 19 (35 U.S.C. 371(c)(3)).</p> <p>    a. <input type="checkbox"/> are transmitted herewith (required only if not transmitted by the International Bureau).</p> <p>    b. <input type="checkbox"/> have been transmitted by the International Bureau.</p> <p>    c. <input type="checkbox"/> have not been made; however, the time limit for making such amendments has NOT expired.</p> <p>    d. <input checked="" type="checkbox"/> have not been made and will not be made.</p> <p>8. <input type="checkbox"/> A translation of the amendments to the claims under PCT Article 19 (35 U.S.C. 371(c)(3)).</p> <p>9. <input type="checkbox"/> An oath or declaration of the inventor(s) (35 U.S.C. 371(c)(4)).</p> <p>10. <input type="checkbox"/> A translation of the annexes to the International Preliminary Examination Report under PCT Article 36 (35 U.S.C. 371(c)(5)) and/or amendments under Article 34.</p>			
<b>Items 11. to 16. Below concern other document(s) or information included:</b>			
<p>11. <input type="checkbox"/> An Information Disclosure Statement under 37 CFR 1.97 and 1.98.</p> <p>12. <input type="checkbox"/> An assignment document for recording. A separate cover sheet in compliance with 37 CFR 3.28 and 3.31 is included.</p> <p>13. <input type="checkbox"/> A FIRST preliminary amendment.</p> <p>    <input type="checkbox"/> A SECOND or SUBSEQUENT preliminary amendment.</p> <p>14. <input type="checkbox"/> A substitute specification.</p> <p>15. <input type="checkbox"/> A change of power of attorney and/or address letter.</p> <p>16. <input checked="" type="checkbox"/> Other items or information: copy of Letter and Amendments Under Article 34, Return Postcard</p>			

JC10 Rec'd PCT/PTO 07 MAR 2002

U.S. APPLICATION NO. If known, see 37 CFR 1.500		INTERNATIONAL APPLICATION NO. PCT/US00/26522		CASE NO. 10541-1323																	
17. <input checked="" type="checkbox"/> The following fees are submitted: <b>Basic National Fee (37 CFR 1.492(a)(1)-(5)):</b> Search Report has been prepared by the EPO or JPO .....\$890.00  International preliminary examination fee paid to USPTO (37 CFR 1.492(a)(1)) .....\$710.00  No international preliminary examination fee paid to USPTO (37 CFR 1.482) but international search fee paid to USPTO (37 CFR 1.492(a)(2)) .....\$740.00  Neither international preliminary examination fee (37 CFR 1.482) nor international search fee (37 CFR 1.492(a)(3)) paid to USPTO.....\$1,040.00  International preliminary examination fee paid to USPTO (37 CFR 1.482) and all claims satisfied provisions of PCT Article 33(1)-(4) .....\$100.00  <b>ENTER APPROPRIATE BASIC FEE AMOUNT</b>  Surcharge of \$130.00 for furnishing the oath or declaration later than <input type="checkbox"/> 20 <input type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(e)). <table border="1"><thead><tr><th>Claims</th><th>Number Filed</th><th>Number Extra</th><th>Rate</th></tr></thead><tbody><tr><td>Total Claims</td><td>20 - 20 =</td><td>0</td><td>x \$ 18.00</td></tr><tr><td>Independent Claims</td><td>3 - 3 =</td><td>0</td><td>x \$ 84.00</td></tr><tr><td>Multiple dependent claim(s) if Applicable)</td><td></td><td>0</td><td>+ \$280.00</td></tr></tbody></table> TOTAL OF ABOVE CALCULATIONS = Reduction by ½ for filing by small entity, if applicable. Verified Small Entity statement must also be filed. (Note 37 CFR 1.9, 1.27, 1.28)  SUBTOTAL = Surcharge of \$130.00 for furnishing the English translation later than the <input type="checkbox"/> 20 <input type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(f)).  TOTAL NATIONAL FEE= Fee for recording the enclosed assignment (37 CFR 1.21(h)). The assignment must be accompanied by an appropriate cover sheet (37 CFR 3.28, 3.31), \$40.00 per property +  TOTAL FEES ENCLOSED=				Claims	Number Filed	Number Extra	Rate	Total Claims	20 - 20 =	0	x \$ 18.00	Independent Claims	3 - 3 =	0	x \$ 84.00	Multiple dependent claim(s) if Applicable)		0	+ \$280.00	CALCULATIONS	PTO USE ONLY
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c. <input checked="" type="checkbox"/> The Commissioner is hereby authorized to charge any additional fees which may be required, or credit any overpayment to Deposit Account No. 06-1500. A duplicate copy of this sheet is enclosed.																					
NOTE: Where an appropriate time limit under 37 CFR 1.494 or 1.495 has not been met, a petition to revive (37 CFR 1.137(a) or (b)) must be filed and granted to restore the application to pending status.																					
Send All Correspondence to: Brinks Hofer Gilson & Lione P.O. Box 10395 Chicago, IL 60610				 Signature Steven L. Oberholtzer Name 30,670 Registration Number																	

## TITLE

## VEHICLE IMPACT SENSING SYSTEM

Cross Reference to Related Application

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This application claims the benefit of United States Provisional Application No. 60/156,165, filed September 27, 1999

FIELD OF THE INVENTION

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The present invention relates to a sensing system employed to detect vehicular impact events; and more particularly to a vehicular impact sensing system that utilizes sensors to directly detect vehicle deformation by impact events and actuate restraints, such as inflatable restraints, in the motor vehicle.

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BACKGROUND OF THE INVENTION

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Almost all passenger motor vehicles presently produced include some type of impact deployed restraint system to protect vehicle occupants, or others, during a vehicle impact event. Such restraint systems may include, for example, front and side airbags within the passenger compartment, side curtains, inflatable seat belts, and seat belt pretensioners. A restraint system may also include deployable restraints for the protection of pedestrians involved in impacts with the vehicle, such as pedestrian airbags and hood release mechanisms. Sensing systems typically control the deployment of such restraints by detecting the occurrence of a vehicle impact event.

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During most impact events, the opportunity to provide occupant restraint exists only for a very brief period of time. Furthermore, inadvertent deployment of a restraint, such as an airbag, is undesirable. Therefore, to be most effective, impact deployed restraints must deploy quickly when needed, and only when actually needed. To this end, impact sensors must be able to discriminate between severe and relatively harmless impact events and also be insensitive to mechanical inputs which are not associated with crash events. Most importantly, however, the design of the sensor must allow for

rapid detection of the impact event and transmission of relevant information to allow for effective deployment decisions. The need for a sensor which allows for rapid deployment decisions is particularly great with side airbags, where the crush zone is much smaller than that associated with front airbags, and the time available for a deployment decision is likewise shorter.

Several types of sensors have been used for detection of impact events in vehicles. For example, sensors comprised of piezoelectric cables, accelerometers, pressure sensors and crush-zone switches, have been utilized. While these sensors can operate adequately, it is desirable to improve the ability of vehicle impact sensing systems to discriminate between impact events, such as vehicle crashes, that warrant deployment of a passive restraint, and those that do not, such as a minor impact with a shopping cart. Furthermore, it is desirable to improve the ability of the sensor to provide information regarding the impact, such as its location and relative size, thereby increasing the effectiveness of subsequent deployment decisions.

Consequently, there is a need for an impact sensing system that utilizes sensors capable of relaying information about an impact and making deployment decisions based on such information.

#### SUMMARY OF THE INVENTION

In its embodiments, the present invention comprises a vehicle sensing system that utilizes sensor elements to directly detect deformation of the vehicle and provide information regarding the impact. Direct detection of vehicle deformation, as opposed to indirect detection, allows the sensor to relay more accurate and detailed information regarding the impact event. As a consequence, the sensing system according to the present invention has an ability to discriminate among impact events, and allows for effective deployment decisions.

The sensing system of the present invention includes a sensor element for such direct detection of vehicle deformation. The sensor is mounted in a manner that allows the sensor to directly detect an impact event. That is, the sensor operates as a consequence of its direct physical involvement in the

impact. The sensor is in electronic communication with a controller, which receives and interprets electronic signals from the sensor.

The sensing system of the present invention can be utilized to directly obtain information about impact events in a variety of vehicle locations. For example, sensors can be located in the vehicle door to gather information concerning side impacts. Likewise, a sensor can be embedded directly into a vehicle bumper to obtain information regarding frontal impacts. Wherever located, the sensor elements provide information regarding an impact, allowing for more effective deployment decisions. The sensor element preferably constitutes a bend sensitive resistance element having conductive layers such as an ink which has been printed onto a substrate and treated to produce cracks in its structure. When the bend sensitive resistance element is bent, such as occurs in a vehicle crash, the cracks open and increase the resistance of the element. The bend sensitive resistance element may be a single unitary element, or a plurality of independent elongate elements horizontally situated so as to be capable of providing azimuthal resolution of the impact event. The bend sensitive resistance element may either be disposed on a structural element of the vehicle, such as within a vehicle door, or contained within a sealed housing. Use of a sealed housing protects it from environmental contamination while also imparting a modular design that facilitates installation. Furthermore, the housing may define functional elements that increase the capabilities of the sensing system. For example, the housing may define crush actuators that facilitate the transmission of the impact to the resistance element. Means are adapted for mounting the housing adjacent a structural member of the vehicle, and extending generally along the member.

The controller subsequently makes deployment decisions based on the signals received from the sensor element. The present invention further contemplates a method of discriminating among impact events, the method comprising the steps of: directly sensing vehicle deformation via the sensor; producing a corresponding electronic deformation signal; determining the severity of the impact as compared to a threshold value; and actuating at least

one deployable restraint if the threshold is exceeded by the severity of the impact.

Accordingly, an object of the present invention is to provide a sensing system that employs a sensor element to directly detect vehicle deformation and subsequently to provide an electronic signal containing information regarding the deformation.

Another object of the present invention is to provide a restraints control module which utilizes the information within the electronic signal to make deployment decisions for the restraints of the vehicle.

An advantage of the present invention is that the sensing system can include sensor elements arranged in a manner that provides a degree of azimuthal resolution regarding deformation caused by an impact event, allowing the sensors to provide more specific information regarding the impact.

Another advantage of the present invention is that the sensor element provides a variable output that is used to discriminate between various impact situations, thus improving passive restraint deployment decisions.

Further objects and advantages of the present invention will become apparent by reference to the following description of the preferred embodiment and appended drawings wherein like reference numbers reflect the same feature, element or component.

#### BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a schematic plan view of a vehicle, including sensor elements, in accordance with the present invention;

Figure 2 is a schematic side view of a vehicle door, with a sensor element mounted thereon in accordance with the present invention;

Figure 3 is a schematic plan view of a vehicle bumper with a sensor assembly associated therewith in accordance with the present invention;

Figure 4 is a schematic view of a unitary bend sensitive resistance element in accordance with the present invention;

Figure 5 is a schematic view of a plurality of deformation sensor elements capable of providing azimuthal resolution in accordance with the present invention;

Figure 6A - 6C are graphical illustrations of the approach of the side of a vehicle containing a deformation sensor element to a pole and impact therewith, in accordance with the present invention; and

Figures 7A - 7C are graphical illustrations of the sensor output, corresponding to the impact depicted in Figures 6A - 6C, respectively.

#### DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

A vehicle 10 having several deployable restraints and including the present invention is illustrated in Figures 1 and 2. The vehicle has front 12 and rear 14 seats in a passenger compartment 16. Mounted in proximity to each seat is a seat belt 18, each of which may be equipped with pretensioners 20 as deployment restraints. Mounted in front of the two front seats 12 are front airbags 22. The illustrated vehicle 10 includes two front doors 24 and two rear doors 25, all of which may include a side airbag 26 mounted alongside, adjacent the front 12 and rear 14 seats. The vehicle 10 has a front bumper 28 with a pedestrian airbag 30 mounted in proximity to the bumper 28.

The vehicle 10 may be equipped with accelerometers, a first frontal accelerometer 32 oriented to sense longitudinal acceleration of the vehicle and a second side accelerometer 34 oriented to sense side-to-side (i.e., lateral) acceleration. Alternatively, the two accelerometers 32, 34 can be replaced with a single dual-axis acceleration sensor if so desired. These accelerometers 32, 34 are electronically connected to and in communication with a restraints control module 36.

The impact sensing system 35 of the present invention comprises deformation sensor elements 38 located at various positions throughout the vehicle, a restraints control module 36, and electrical connections 40 between the sensor elements 38 and the restraints control module 36. The sensor elements 38 of the current invention may be utilized in several areas of the

vehicle. Generally, the sensor elements 38 will be mounted in areas around the body of the vehicle 10 in which impact sensing is desired, i.e., areas in which impact events are known to occur. For example, the sensor elements 38 may be disposed within a door 24 of the vehicle 10 for detecting side impact events. Also, a sensor element 38 may be disposed near or within a bumper 28 of the vehicle 10. So disposed, the element 38 can be utilized to monitor for impact events involving pedestrians. Other locations may, of course, be desirable. No matter where located, the sensor element 38 is disposed in a manner that allows direct detection of an impact event. That is, the sensor element 38 is disposed in a manner that ensures its physical involvement in an impact event generating sufficient deformation of the vehicle 10. The term deformation sensor is used to describe sensors capable of this direct physical involvement in vehicle impact events causing sufficient deformation of the vehicle 10. For example, as shown in Figure 2, the sensor element 38 may be disposed on a structural element of a vehicle door 24. In this configuration, the sensor element 38 will directly participate in a side impact event affecting the vehicle door 24. Also, for monitoring pedestrian and frontal impact events, the sensor element 38 may be directly embedded in the compressible material of the bumper 28. The position of the sensor element 38 allows the sensing system 35 to discriminate among impact events. For example, the outer skin 42 of a vehicle door 24 and the outer layer of a vehicle bumper 28 are frequently exposed to impact events not warranting deployment of a passive restraint. A slight indentation to either of these structural elements does not warrant deployment. Therefore, positioning the sensor element 38 on the surface of either of these structural elements may lead to unnecessary deployment. Positioning the sensor element 38 sufficiently underneath the outer skin 42 of the structural element while ensuring its participation in significant impact events eliminates such unnecessary deployments.

Figure 2 illustrates an example of the sensor element 38 mounted in a vehicle door 24. The sensor element is positioned underneath the outer skin 42 and near a main structural element, such as a structural reinforcement



beam 44. The sensor element 38 can be mounted thereto via attachment points 46. Alternatively, the sensor element 38 can be disposed within a housing member (not illustrated), and the housing member can be mounted securely to the reinforcement beam 44 via attachment points 46. The attachment points 46 can be fasteners, welding, etc., so long as the sensor element 38 and/or housing is securely and rigidly mounted to the reinforcement beam 44.

Figure 3 illustrates an example of the sensor element 38 mounted near the front bumper 28. The sensor element 38 is located behind the outer layer of the bumper 28, and may either be directly embedded in the compressible material of the bumper 28, or be mounted behind the bumper 28 in a manner similar to that described above for the sensor element 38 located within a vehicle door 24. This sensor element 38 will detect impacts to the front bumper 28, and demonstrates the ability of the sensing system 35 to discriminate among impact events based on the severity of the event. Depending on the severity and the force of the impact detected by the sensor element 38, the restraints control module 36 may deploy either a pedestrian airbag 30, for minor impacts typical of those with pedestrians, or the front 22 and/or side 26 airbags for major impacts such as vehicle crashes. The ability to discriminate between these two very different types of impacts is developed more fully below.

Each sensor element 38 is in electrical communication with the restraints control module 36 via electrical connections 40. There may be a signal-processing module 48 electrically situated between the sensor elements 38 and the restraints control module 36, i.e., the signal processing module 48 is electrically connected to both the sensor elements 38 and the restraints control module 36. The restraints control module 36 is electrically connected to and in communication with the deployable restraints of the vehicle 10.

In the preferred embodiment, the sensor element 38 constitutes a bend sensitive resistance element 50. Bend sensitive resistance elements, such as the flexible potentiometer disclosed in U.S. Patent No. 5,583,476 to Langford,

provide electrical signals that vary as the element is deformed. A bend sensitive resistance element 50 is only one example of the type of sensor that can be used as the sensor element 38 in the sensing system 35 of the present invention. As such, the specific example of a bend sensitive resistance element 50 is only illustrative in nature and is not intended to limit the scope of the present invention in any way.

Preferably, the bend sensitive resistance element 50 is comprised of a rectangular ink strip 52 composed of a conductive ink which has been treated to produce cracks in the ink, a flexible substrate 54, and electrical connectors 56 for connecting the conductive ink strip 52 and the restraints control module 36. The flexible substrate 54 is preferably about 1" wide and has a length approximately equal to the structural element being monitored. In one embodiment, the ink strip 52 constitutes a single continuous strip of the conductive ink having a length slightly less than that of the flexible substrate. Preferable in this embodiment, the ink strip 52 is approximately  $\frac{1}{4}$ " in height, and has a length approximately equal to the length of the structural element to be monitored. For example, for a bend sensitive resistance element 50 utilized to monitor for side impacts, the ink strip 52 preferably has a length approximately equal to the length of the appropriate vehicle door 24 and is disposed on a flexible substrate 54 slightly longer in length.

It will be appreciated that the flexible substrate 54 can vary significantly from the dimensions detailed above. For example, the substrate 54 can take a size and form approximately equal to the interior space of a door 24 panel. In this configuration, ink strips 52 could be disposed in a variety of patterns along the flexible substrate 54, providing a multitude of deformation sensors. The patterns could be designed to mimic high-probability impact sites. It will be further appreciated that the ink strips 52 can vary from the dimensions detailed above to meet specific impact monitoring needs.

In an alternate embodiment illustrated in Figure 5, the conductive ink is arranged into several smaller strips 52 each in independent electrical communication with the restraints control module 36. In this embodiment, the smaller ink strips 52 are disposed horizontally relative to each other, i.e., end-

to-end, along a unitary flexible substrate 54. The smaller ink strips are preferably about ¼" in height by approximately 4" in length. As in the previous embodiment, the flexible substrate 54 is preferably about 1" in height and has a length approximately equal to the structural element being monitored. An appropriate number of smaller ink strips 52 necessary to span the length of the flexible substrate 54 is disposed on the flexible substrate 54. It has been determined that, for a typical front vehicle door 24, seven ink strips 52 of the preferable dimensions, laid end-to-end on the flexible substrate 54 provide adequate coverage of the span.

Arranged in this manner, the smaller ink strips 52 act as individual bend sensitive resistance elements 50, providing a degree of azimuthal resolution. For example, when an impact event occurs near the latch of the door 24, causing deformation only in that area, the element 50 located in that area will deform, and therefore it will be the only element 50 that relays a deformation signal to the restraints control module 36. This localization of the impact will allow the restraints control module 36 to better discriminate among severe and non-severe impact events. In contrast, if the element 50 constitutes a single, continuous ink strip 52 along the span, no such localization of the impact occurs. For example, when an impact occurs near the latch, the element 50 relays an impact signal. Because localized elements 50 were not present, though, the signal does not relay information regarding the locality of the impact beyond the general area of the vehicle door 24. Consequently, the restraints control module 36 does not have information regarding the precise location of the impact when making a subsequent deployment decision. Furthermore, this arrangement of a plurality of bend sensitive resistance elements 50 provides an ability to resolve the location and width of an impact event relative to the vehicle 10 by comparing the extent of deformation between neighboring bend sensitive resistance elements 50.

The conductive ink strip 52 of the bend sensitive resistance element 50 is printed onto the flexible substrate 54. Preferably, the substrate 54 is a flexible material such as polyamide. Polyester or other suitable materials

capable of providing the necessary flexibility may also be used. The flexible nature of the substrate 54 allows the bend sensitive resistance element 50 to be disposed along a non-linear surface. Also, the flexible substrate 54 provides the flexibility necessary to allow the ink strips 52 to structurally react in response to impact events, which is necessary for proper operation of the bend sensitive resistance element 50, and consequently the sensing system 35. The flexible substrate 54 may have an adhesive backing which facilitates placement on structural elements or in a housing.

The cracks are small, interspersed fissures in the ink strip 52 of the bend sensitive resistance element 50. The cracks are randomly spaced and oriented throughout the ink strip 52. The cracks are disposed along a single side of the strip 52, making the bend sensitive resistance element 50 sensitive in only one direction. When used to monitor for the occurrence of side impact events in a vehicle door 24, the surface having the cracks is typically directed toward the passenger compartment 26 of the vehicle 10. As the bend sensitive resistance element 50 is bent inward, such as when a side impact occurs, the cracks open and increase the resistance of the element 50. This change in resistance can be detected by the restraints control module 36, which continually monitors the resistive output of the element 50.

In addition to bend sensitive resistance elements 50, the sensor element 38 may be any other type of sensor element 38 capable of being disposed in a manner that allows direct physical involvement in an impact and gathering and relaying information regarding the impact. That is, the sensor element 38 may be any other type of deformation sensor element. For example, the sensor element 38 may be a piezoelectric cable or a fiber-optic cable. No matter the type of deformation sensor utilized, the sensor element 38 can be either a unitary item spanning the length of a vehicle structural element, or may be a plurality of elongate sensor elements 38 horizontally situated so as to be capable of providing azimuthal resolution of impact events.

Turning now to the operation of the sensing system 35 of the present invention. As discussed above, the sensor element 38 of the present

invention is able to directly participate in a vehicle impact event occurring in the area of the vehicle 10 in which the sensor element 38 is positioned. The sensor element 38 provides a variable output that is proportional to the extent of deformation induced in the sensor element 38 by an intruding object driving the impact event. It will be noted that the bend sensitive resistance element 50 of the preferred embodiment, due to its flexible nature and ability to have an adhesive backing on the flexible substrate 54, is particularly easy to mount in various locations of the vehicle 10 such that it will directly participate in and therefore detect an impact, and subsequently relay information regarding the impact event.

Figures 6a - 6c show an impact event involving a pole 58 and a vehicle 10 containing a sensing system 35 according to the present invention. The door 24 of the vehicle 10 contains a sensor element 38 in communication with a restraints control module 36. The sensor element 38 is positioned underneath the outer skin 42 of the door 24. The figure illustrates the physical consequences of the impact over time. As the impact progresses, the pole 58 first deforms the outer skin 42 of the vehicle door 24. As shown in Figure 6b, the sensor element 38 is not involved at this point due to its position relative to the outer skin 42. However, as shown in Figure 6c, once the impact progresses to a point where the sensor element 38 is situated, the pole 58 actually deforms the sensor element 38. At this point, the sensor element 38 is directly participating in the impact event, which is necessary for the operation of deformation sensors. As the impact progresses further, the sensor element 38 deforms further. The sensor element 38 provides an output signal 60 that, when altered, indicates the occurrence of an impact event. For example, fiber optic deformation sensors provide an output signal 60 that consists of the transmission of light. In the preferred embodiment, the resistance of the bend sensitive resistance element 50 is the output signal 60, and increases as deformation progresses due to increased opening of the cracks in the ink strip 52. The restraints control module 36 detects any change in the output signal 60, as described below, and makes a deployment decision based thereon.

Figures 7a - 7c illustrate a corresponding output signal 60 transmitted by the sensor element 38 during the impact event depicted in Figures 6a -6c. As the impact event progresses over time, the output signal 60 varies depending on the extent of deformation of the sensor element 38. For the preferred embodiment, which utilizes a bend sensitive resistance element 50, the output signal 60 corresponds to the resistance of the sensor element 38. In Figure 7a, before the impact event has occurred, the output signal 60 remains constant at a threshold output level 62. As the pole 58 deforms the outer skin 42 of the door 24 but has yet to reach the sensor element 38, the electrical output signal 60 remains constant at the threshold level 62, as illustrated in Figure 7b. Once the sensor element 38 is involved in the impact event, and deformation of the sensor element 38 occurs, the output signal 60 changes to reflect the severity of the impact.

The amplitude 64 of the change in the output signal 60 indicates the extent of the deformation. That is, as more deformation is imposed on the sensor element 38, the output signal 60 changes more dramatically from the threshold output level 62. For the preferred embodiment utilizing bend sensitive resistance elements 50, it has been observed that the resistance typically changes by a factor of approximately ten when deployment - type events are encountered. The output signal 60 of the sensor element 38 will return to its original value, i.e., the threshold output level 62, when and if the sensor element 38 returns to its original and undeformed state. The slope 66 of the change in the output signal 60 indicates the rate at which the deformation occurred. If deformation occurs rapidly, the time required to achieve the change in the output signal 60 is relatively brief, producing a steep slope 66. Conversely, if the deformation occurs relatively slowly over time, the slope 66 will be correspondingly gradual in nature. Both the amplitude 64 and the slope 66 of the change in the output signal 60 can be used by the restraints control module 36 to make more effective deployment decisions. For example, if the amplitude 64 indicates a relatively severe impact event, the restraints control module 36 can deploy restraints to a greater extent, such as involving more restraints or deploying one restraint

more fully. Also, if the slope 66 indicates a relatively slow impact event, the restraints control module 36 can slow down the rate of deployment.

The output signal 60 is sent via the signal-processing module 48 to the restraints control module 36, which then interprets the signal 60 to discriminate between different types and severity of impacts. Given that different types of objects involved in impact events, such as poles 58, barriers, pedestrians and other vehicles, will produce different output signals 60 for a given speed and acceleration of the vehicle 10 during the impact event, the signal 60 will vary accordingly. The ability of the sensing system 35 of the present invention to provide azimuthal resolution of an impact event adds another degree of variance to the output signal 60. The resulting ability to distinguish, for example, pole-impact events from low-speed barrier impacts, will provide a more accurate decision from the restraints control module 36 for when to deploy a restraint device, which restraint to deploy, and the extent of such deployment. Furthermore, the ability to determine the location and width of impact with the vehicle 10 will allow for more effective decisions regarding which restraints need be deployed.

The restraints control module 36 includes hardware and/or software for processing incoming output signals 60, determining if a passive restraint threshold has been met and sending a deployment signal to the passive restraints, such as the front airbags 22, the side airbags 26, and/or the pedestrian airbag 30.

In order to further improve impact determination and passive restraint firing decisions, one may wish to employ the output signal 60 from the sensor elements 38 of the present invention along with the output from the accelerometers 32, 34. The accelerometers 32, 34 are illustrated in Figure 1 and also provide output signals processed by the restraints control module 36. While accelerometers are illustrated in the preferred embodiment, they are not necessary for the operation of the sensor elements 38 of the present invention.

For example, the particular sensor element 38 near the impact location may be used as the primary impact detection sensor, with the centrally

mounted accelerometers employed as safing sensors. In this way, the characteristics of the strain detected by the sensor element 38 may be tempered by the amount of acceleration experienced by the vehicle as is detected by one or both of the accelerometers 32, 34. Another example of impact detection in which the different sensors are employed may include employing the accelerometers 32, 34 as the primary sensors for impact events, and modifying the thresholds for the deployment decision based upon the strain detected by a particular one of the sensor elements 38. No matter if the sensor element 38 or the accelerometers 32, 34 are utilized as the primary sensors, the azimuthal resolution provided by the sensor elements 38 can be utilized in conjunction with output from the accelerometers 32, 34 to resolve the localization and/or width for an impact event. This combination of impact information provides for a further degree of tempering, and increasing the number of possible deployment scenarios.

The foregoing disclosure is the best mode devised by the inventors for practicing the invention. It is apparent, however, that vehicle impact sensing systems incorporating modifications and variations will be obvious to one skilled in the art of impact sensors and systems. Inasmuch as the foregoing disclosure is intended to enable one skilled in the pertinent art to practice the instant invention, it should not be construed to be limited thereby but should be construed to include such aforementioned obvious variations and be limited only by the spirit and scope of the following claims:



**WE CLAIM:**

1. A vehicle impact sensing system for detecting vehicular impacts causing structural elements of a vehicle to deform, comprising, in combination,

5           at least one bend sensitive resistance element disposed along a structural element of said vehicle and being capable of generating a variable resistance output, the bend sensitive resistance element having a strip of conductive ink containing a plurality of cracks along a surface thereof,

at least one deployable restraint disposed within said vehicle,  
10     and  
            a controller in electrical communication with said at least one bend sensitive resistance element, said controller being capable of detecting changes in said variable resistance output.

2. The vehicle impact sensing system of claim 1 wherein said at  
15 least one bend sensitive resistance element is a single elongate sensor  
disposed on a flexible substrate.

3. The vehicle impact sensing system of claim 1 wherein said at least one bend sensitive resistance element comprises a plurality of individual sensors horizontally disposed on a flexible substrate,

20               whereby said plurality of individual sensors is capable of  
providing a degree of azimuthal resolution of said vehicular impacts.

4. The vehicle impact sensing system of claim 1 wherein said structural element of said vehicle is a structural reinforcement beam of a door of said vehicle.

25            5.        The vehicle impact sensing system of claim 1 wherein said structural element of said vehicle is a bumper of said vehicle.

6. The vehicle impact sensing system of claim 1 wherein said at least one passive restraint is a side airbag.

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7. The vehicle impact sensing system of claim 1 wherein said at least one passive restraint is a pedestrian airbag.

8. A vehicle impact sensing system for detecting vehicular impacts causing structural elements of a vehicle to deform, comprising,  
a plurality of deformation sensor elements horizontally disposed along a structural element of said vehicle, each of said plurality being capable  
5 of generating a variable output signal,  
at least one deployable restraint disposed within said vehicle,  
and  
a controller in electrical communication with said plurality of deformation sensor elements and said at least one deployable restraint, said  
10 controller being capable of detecting changes in said variable output signal,  
whereby said plurality of deformation sensor elements is capable of providing a degree of azimuthal resolution of said vehicular impacts.
9. The vehicle impact sensing system of claim 8 wherein said  
15 plurality of deformation sensor elements is a plurality of elongate bend sensitive resistance elements.
10. The vehicle impact sensing system of claim 8 wherein said variable output signal of said deformation sensor element is the resistance of said deformation sensor element.
- 20 11. The vehicle impact sensing system of claim 8 wherein said plurality of deformation sensor elements is a plurality of piezoelectric cables.
12. The vehicle impact sensing system of claim 8 wherein said plurality of deformation sensor elements is a plurality of optical fibers and said variable output is the transmission of light.
- 25 13. The vehicle impact sensing system of claim 8 wherein said structural element of said vehicle is a structural reinforcement beam of a door of said vehicle.

14. The vehicle impact sensing system of claim 8 wherein said structural element of said vehicle is a bumper of said vehicle.

15. A vehicle impact sensing system for detecting vehicular impacts causing structural elements of a vehicle to deform, comprising, in combination:

- 5 a plurality of deformation sensor elements horizontally disposed along a structural element of said vehicle, each of said plurality being capable of generating a variable output signal,
- at least one deployable restraint disposed within said vehicle,
- at least one accelerometer sensor, and
- 10 a controller in electrical communication with said plurality of deformation sensor elements, said accelerometer sensor and said at least one deployable restraint, said controller being capable of detecting changes in said variable output and deploying said at least one passive restraint.

16. The vehicular impact sensing system of claim 15 wherein said at least one accelerometer sensor is oriented to detect acceleration in a longitudinal direction of said vehicle.

17. The vehicular impact sensing system of claim 15 wherein said at least one accelerometer sensor is oriented to detect acceleration in a lateral direction of said vehicle.

18. The vehicle impact sensing system of claim 15 wherein said at least one passive restraint is a side airbag.

19. The vehicle impact sensing system of claim 15 wherein said at least one passive restraint is a front airbag.

20. The vehicle impact sensing system of claim 15 wherein said at least one passive restraint is a pedestrian airbag.

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[US/US]; 13925 Monarch Drive, South Lyon, MI 48178 (US). CHI, David, Ming [US/US]; 2926 Courville Drive, Bloomfield Hills, MI 48302 (US).

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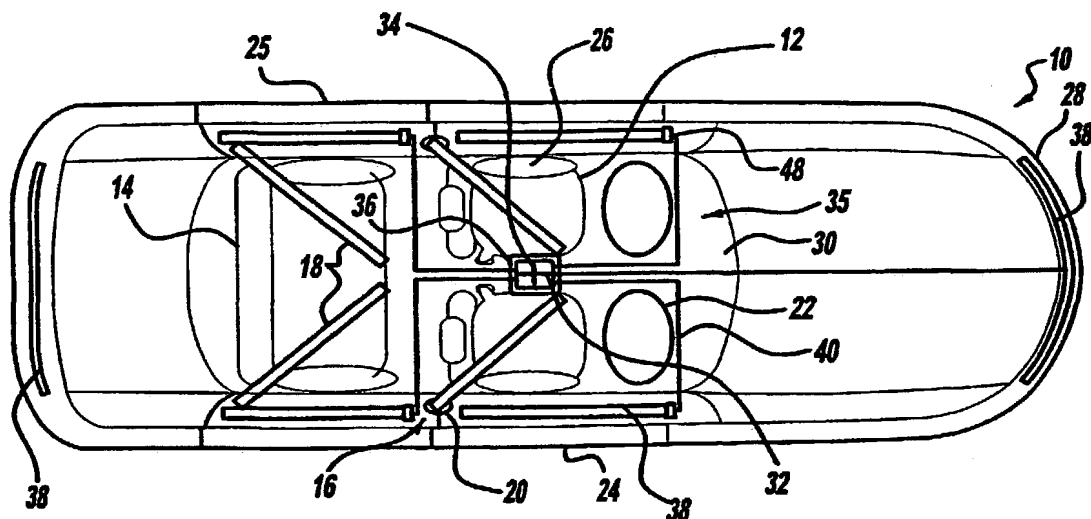
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(72) Inventors; and  
(75) Inventors/Applicants (*for US only*): ZORATTI, Paul, K.

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(54) Title: VEHICLE IMPACT SENSING SYSTEM



(57) Abstract: A vehicle impact sensing system includes one or more sensor elements (38) capable or directly detecting vehicle deformation occurring as a consequence of the impact event. Upon deformation of the sensor element (38), the control module (36) receives impact signals from the sensor elements and discriminates between impact events that warrant deployment of a passive restraint, such as a side air bag (26), and those that do not.

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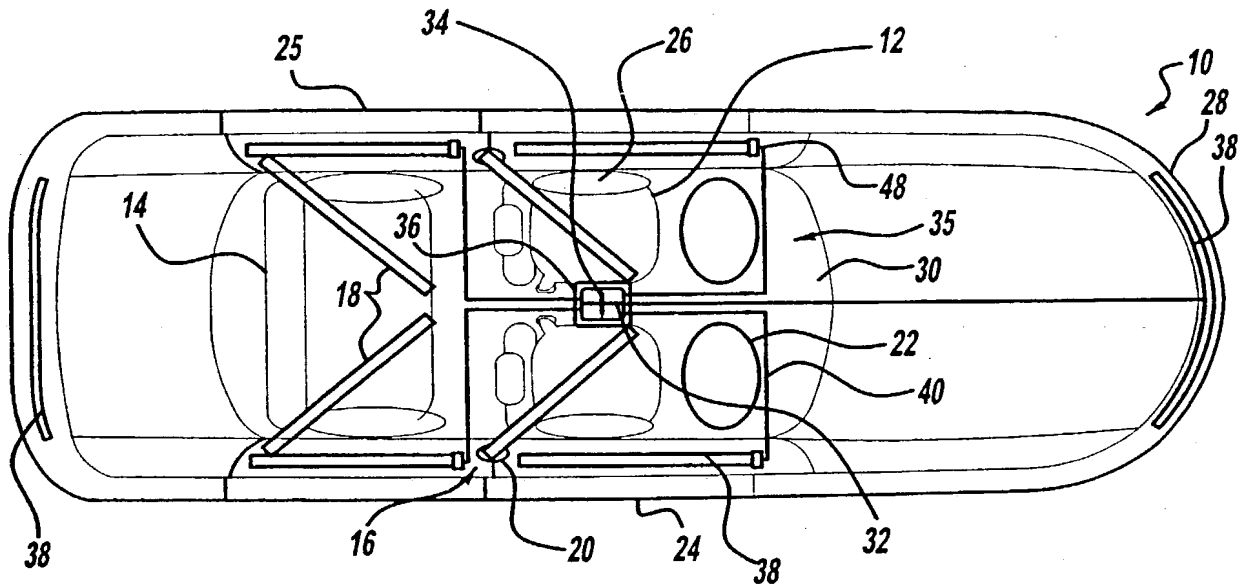


Figure - 1

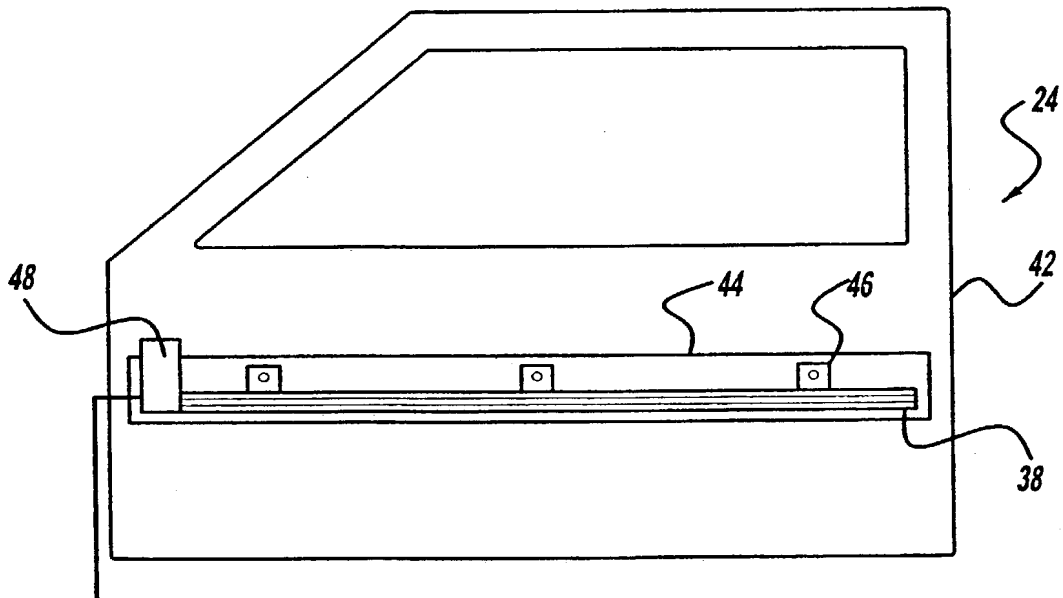


Figure - 2

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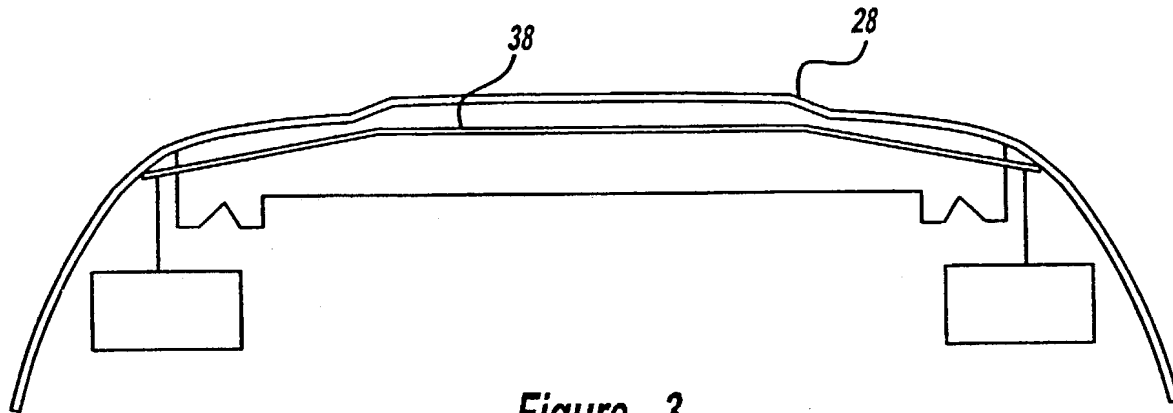


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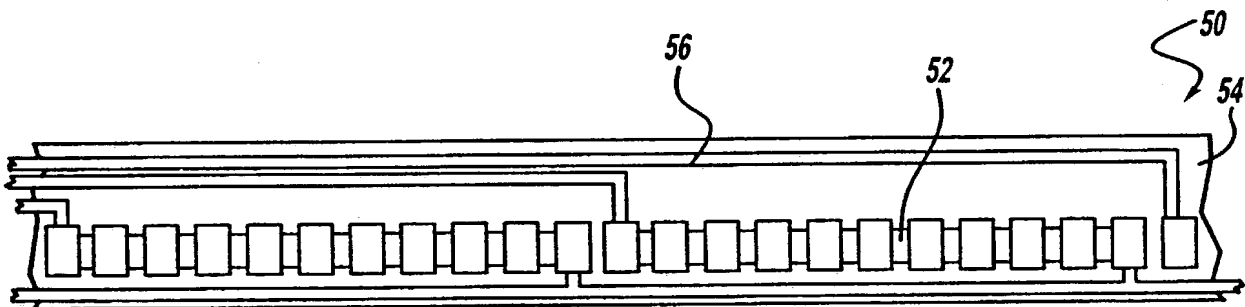


Figure - 4

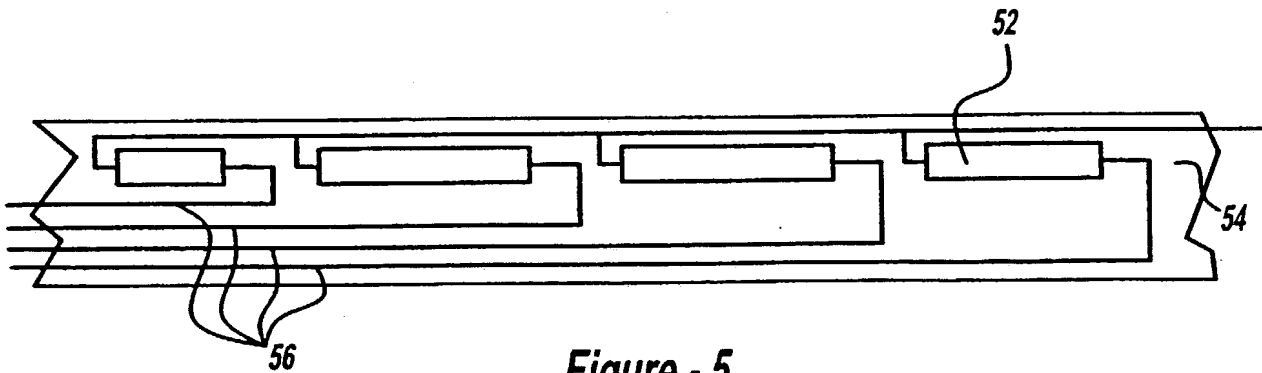


Figure - 5



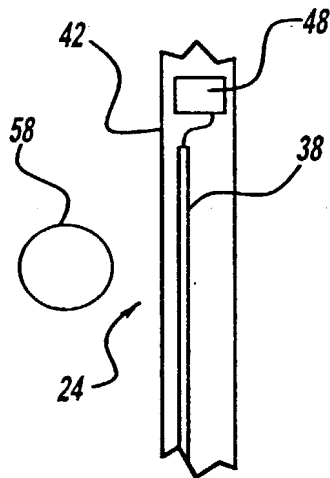


Figure - 6a

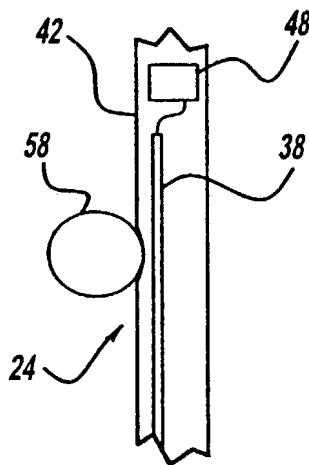


Figure - 6b

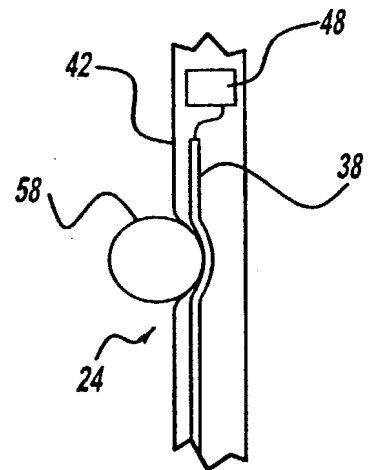


Figure - 6c

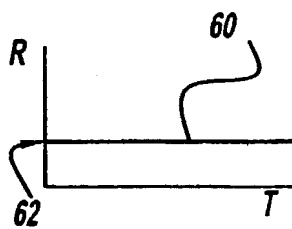


Figure - 7a

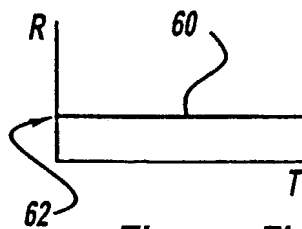


Figure - 7b

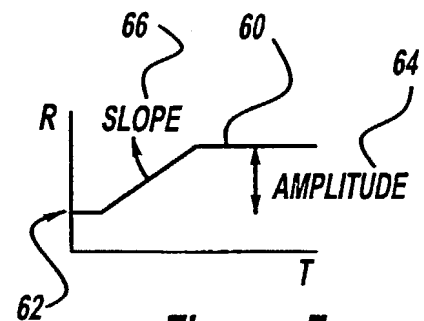
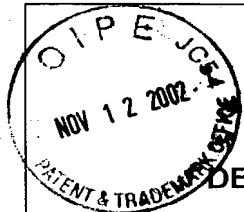


Figure - 7c



Attorney Docket No.: 10541-1323

Visteon Case No.: 199-0688

## DECLARATION AND POWER OF ATTORNEY ORIGINAL APPLICATION

As a below named inventor, I hereby declare:

My residence, post office address and citizenship are as stated below next to my name;

I believe I am the original, first and sole inventor or an original, first and joint inventor of the subject matter that is claimed and for which a patent is sought on the invention entitled:

### VEHICLE IMPACT SENSING SYSTEM

the specification of which was filed on March 7, 2002 and assigned U.S. Serial No. 10/070,884.

I hereby state that I have reviewed and understand the contents of the above identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge my duty to disclose to the United States Patent and Trademark Office all information that I know to be material to the patentability of this application as defined in Title 37 C.F.R. § 1.56.

I hereby claim foreign priority benefits under Title 35, United States Code, Section 119(a)-(d) or Section 365(b) of any foreign application(s) for patent or inventor's certificate, or Section 365(a) of any PCT International application which designated at least one country other than the United States, listed below and have also identified below, by checking the box, any foreign application for patent or inventor's certificate or PCT International application having a filing date before that of the application on which priority is claimed.

Prior Foreign Application(s):

Priority Not Claimed

_____ (Number)	_____ (Country)	_____ (Filing Date)	<input type="checkbox"/>
_____ (Number)	_____ (Country)	_____ (Filing Date)	<input type="checkbox"/>
_____ (Number)	_____ (Country)	_____ (Filing Date)	<input type="checkbox"/>

I hereby claim the benefit under 35 U.S. C. Section 119(e) of any United States provisional application(s) listed below:

<u>60/156,165</u> (Application Serial No.)	<u>September 27, 1999</u> (Filing Date)
_____ (Application Serial No.)	_____ (Filing Date)
_____ (Application Serial No.)	_____ (Filing Date)

I hereby claim the benefit under 35 U.S.C. Section 120 of any United States applications(s), or Section 365(c) of any PCT International Application designating the United States, listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States or PCT International application in the manner provided by the first paragraph of 35 U.S.C. Section 112, I acknowledge the duty to disclose to the United States Patent and Trademark Office all information known to me to be material to patentability as defined in Title 37, C.F.R., Section 1.56 which became available between the filing date of the prior application and the national or PCT International filing date of this application.

<u>PCT/US00/26522</u>	<u>September 27, 2000</u>	<u>Pending</u>
(Application Serial No.)	(Filing Date)	(Status: patented, pending, abandoned)
(Application Serial No.)	(Filing Date)	(Status: patented, pending, abandoned)
(Application Serial No.)	(Filing Date)	(Status: patented, pending, abandoned)

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

**POWER OF ATTORNEY:** As a named inventor, I hereby appoint the following attorneys, agents, and each shareholder, attorney of counsel, associate, and employee of Brinks Hofer Gilson & Lione, who is a registered Patent Attorney or registered Patent Agent, my attorney with full power of substitution and revocation to prosecute this application and transact all business in the United States Patent and Trademark Office connected therewith and to act on my behalf before the competent International Authorities in connection with any and all international applications filed by me.

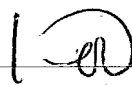

Steven L. Oberholtzer, Reg. No. 30,670  
 David D. Murray, Reg. No. 28,647  
 James E. Stephenson, Reg. No. 17,191  
 Eric J. Sosenko, Reg. No. 34,440  
 Jeffrey M. Cox, Reg. No. 42,445  
 Raymond J. Vivacqua, Reg. No. 45,369  
 J. Matthew Buchanan, Reg. No. 47,459  
 Ryan Kennedy, Reg. No. 48,590

Sujatha Subramaniam, Reg. No. 48,739  
 Douglas D. Fekete Reg. No. 29,065  
 Lawrence G. Almeda, Reg. No. 46,151  
 Gael D. Lindland, Reg. No. 51,952  
 Scott M. Confer, Reg. No. 40,568  
 John Kajander, Reg. No. 47,693  
 Frank Lollo, Reg. No. 48,854

15

Address all correspondence and telephone calls to:

Steven L. Oberholtzer  
 BRINKS, HOFER, GILSON & LIONE  
 P.O. Box 10395  
 Chicago, IL 60610  
 (734) 302-6000

Full name of sole or first inventor	 Paul K. Zoratti	
Sole or first inventor's signature		Date 7/22/02
Residence	13925 Monarch Dr., South Lyon, Michigan 48178	
Citizenship	United States	
Post Office Address	Same As Above	

Full name of second inventor, if any

20  
Jeffery A. Bochenek

23 JUL 02

Second inventor's signature

Date

Residence

Jeff A. Bochenek MI  
4610 Windswept Dr., Milford, Michigan 48380

Citizenship

United States

Post Office Address

Same As Above

Full name of third inventor, if any

30  
David Ming Chi

Third inventor's signature

Date

7/23/02

Residence

David Chi  
~~2026 Courville Dr., Bloomfield Hills, Michigan 48302~~

Citizenship

United States

Post Office Address

Same As Above

Full name of fourth inventor, if any

Fourth inventor's signature

Date

Residence

Citizenship

Post Office Address

Full name of fifth inventor, if any

Fifth inventor's signature

Date

Residence

Citizenship

Post Office Address

Full name of sixth inventor, if any

Sixth inventor's signature

Date

Residence

Citizenship

Post Office Address